1 21 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base near4 station) and (position\$4 same correct\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station) and ((parallel same line same position\$4) 127 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) and ((parallel same line same path) or (concentric same polygon same path)) and (base same receiver) and accelerometer and (path same offset)) and ((QPS same correct\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) 15 211 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) 16 0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((parallel same line same path) or (concentric same polygon same path)) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) 17 336 (GPS same receiver) and accelerometer and (inertial same receiver) and accelerometer and (inertial same path)) and (base same station)) 18 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (concentric same polygon same path) or (concentric same polygon same path) and (c					m'
((parallel same line same path)or(concentric same polygon same path)and (base near4 (path same offset) (vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path))and (base same polygon same path)and (base same station)and (position\$4 same correct\$4) and ((parallel same line same path)or(concentric same polygon same path)and (base same receiver)and accelerometer and (inertial same relative same position\$4) (parallel same line same path)or(concentric same polygon same path)and (base same receiver)and accelerometer and (inertial same relative same position\$4) (upaincle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)and (base same station) (GPS same receiver)and accelerometer and (inertial same relative same position\$4) (uparallel same line same path)and (base same path) (uparallel same line same path)and (base same station)) (uparallel same line same path)and (base same path)and (base same path)and (base same station)) (uparallel same line same path)and (uparallel same line same path)and (uparallel same line same path)and (uparallel same line	L Number	Hits	Search Text	DB	Time stamp
same polygon same path))and (base near4 station) and (position\$4 same correct\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (parallel same relative same position\$4) 127 (GPS same receiver) and accelerometer and (inertial same relative same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (parallel same line same path) or (concentric same polygon same path)) and (logs same receiver) and accelerometer and (inertial same relative same position\$4) 2004/02/12 13: ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same path)) and (base same station)) ((SPS same receiver) and accelerometer and (inertial same path) or (concentric same polygon same path) or (concentric same polygon same path) and (base same station)) ((Vehicle or tractor or aggricultur\$4) and (SPS same receiver) and accelerometer and (inertial same position\$4) ((Vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path) and (base same station)) ((Vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path) and (base same station)) ((SPS same receiver) and accelerometer and (inertial same polygon same path) and (base same station)) ((Vehicle or tractor or aggricult	1	21			2004/02/12 13:56
station) and (position\$4 same correct\$4) and (path same offset) (vehicle or tractor or aggricultur\$4) and (path same offset) (vehicle or tractor) as me path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (path same offset) (path same path) or (concentric same polygon same path) and (path same offset)) and ((path same offset)) and (path same path) and (base same station) 6				1	
(path same offset) (vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path) and (base same (GPS same receiver) and accelerometer and (inertial same relative same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (parallel same relative same position\$4) (cheicle or tractor or aggricultur\$4) and (parallel same position\$4) (cheicle or tractor or aggricultur\$4) and (parallel same path) or (concentric same polygon same path) and (base same station) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) ((GPS same receiver) and accelerometer and (inertial same path) or (concentric same polygon same path) and (base same station)) ((GPS same receiver) and accelerometer and (inertial same path) or (concentric same polygon same path) and (base same station)) ((vehicle or tractor or aggricultur\$4) and (parallel same line same path) or (concentric same polygon same path) and (base same station)) ((vehicle or tractor or aggricultur\$4) and (inertial same position\$4) ((parallel same line same path) or (concentric same polygon same path) and (base same station)) ((parallel same receiver) and accelerometer and (inertial same position\$4)) ((parallel same receiver) and accelerometer and (inertial same position\$4)) ((parallel same receiver) and accelerometer and (inertial same position\$4)) ((parallel same receiver) and accelerometer and (inertial same position\$4)) ((parallel same rec					
Second Company of the content of t				1 '	
((parallel same line same path)or(concentric same polygon same path))and (base same (soly per path))and (path same offset) (GPS same receiver) and accelerometer and (inertial same relative same positions)4) ((vehicle or tractor or aggriculturs)4)and (path same offset) and (GPS same receiver) and (GPS same path) or (concentric same polygon same path)) and (base same preceiver) and accelerometer and (inertial same relative same positions)4) ((vehicle or tractor or aggriculturs)4)and (path same offset) and (GPS same receiver) and accelerometer and (inertial same polygon same path)) and (base same polygon same path)) and (base same polygon same path)) and (base same polygon same path)) and (path same relative same positions)4) ((GPS same receiver) and accelerometer and (inertial same relative same positions)4) and (vehicle or tractor or aggriculturs)4) and (vehicle or tractor or aggriculturs)4) and (vehicle or tractor or aggriculturs)4) and (parallel same line same path) or (concentric same polygon same path)) and (GPS same receiver) and accelerometer and (inertial same positions)4) ((vehicle or tractor or aggriculturs)4) and (vehicle or tractor or aggriculturs)4) and (parallel same line same path) and parallel same lin	_	22			2004/02/12 12:50
same polygon same path))and (base same station) and (posticins%4 same correct\$4) and (path same offset) 127 (GPS same receiver) and accelerometer and (inertial same relative same position\$4) 128 ((vehicle or tractor or aggricultur\$4) and (path same offset) (position\$4) same offset) (position\$4) same path) and (path same offset) and (GPS same receiver) and accelerometer and (inertial same relative same position\$4) same path) and (path same offset) and (GPS same receiver) and accelerometer and (inertial same polygon same path)) and (base same station) (path same offset) and (GPS same receiver) and accelerometer and (inertial same relative same position\$4) (parallel same line same path) or aggricultur\$4) and (parallel same path) and (base same station) (path same relative same position\$4) (parallel same line same path) or aggricultur\$4) and (parallel same position\$4) (parallel same same path) or (concentric same polygon same path) or (concentric same polygon same path) or (concentric same polygon same path) and (parallel same line same path) or (concentric same polygon same pat		22		1	2004/02/12 13.36
station) and (position\$4 same correct\$4) and (path same offset) (GPS same receiver) and accelerometer and (inertial same relative same position\$4) ((vehicle or tractor or aggricultur\$4) and (path same offset)) and (base same station) and (position\$4 same correct\$4) and (path same offset)) and (GPS same receiver) and accelerometer and (inertial same relative same position\$4) ((vehicle or tractor or aggricultur\$4) and (path same offset)) and (GPS same receiver) and accelerometer and (inertial same relative same position\$4) ((parallel same line same path) or (concentric same polygon same path)) and (base same station) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and (path same offset)) and (path same path) or (concentric same polygon same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same relative same position\$4)) (GPS same receiver) and accelerometer and (inertial same path) or (concentric same polygon same path)) and (base same station)) ((vehicle or tractor or aggricultur\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station)) ((vehicle or tractor or aggricultur\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station)) ((vehicle or tractor or aggricultur\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station)) ((vehicle or tractor or aggricultur\$4) and (parallel same line same path) or (concentric same polygon same path) and (base same station)) ((orgh same receiver) and accelerometer and (parallel same line same path) or (concentric same polygon same path) and (base same station)) ((orgh same receiver) and accelerometer and (parallel same path) or (concentric same polygon same path) and (parallel same path) or (concentric same polygon same path) and (parallel same path) and (parallel same path) and (parallel same path) and (parallel same pat				· ·	
(path same offset) (GPS same receiver) and accelerometer and (inertial same relative same position\$4) USPAT; USPGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; USPGPUB; EPO; JPO; DERWENT; IBM TDB USPAT; USPA					
3 127 (GPS same receiver) and accelerometer and (inertial same relative same position\$4) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (parallel same line same path) or (concentric same polygon same path)) and (base same station) and (position\$4) and (GPS same receiver) and accelerometer and (inertial same relative same position\$4) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (concentric same polygon same path)) and (base same station) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (concentric same polygon same path)) and (base same station) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (concentric same polygon same path)) and (concentric same polygon same path)) and (concentric same position\$4) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (concentric same polygon same path)) and (base same station) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (concentric same polygon same path)) and (base same station) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB (concentric same polygon same path) and (concentric same polygon same path)					
(inertial same relative same position\$4) (inertial same line same path)or(concentric same polygon same path)) and (base same receiver) and accelerometer and (inertial same relative same position\$4)) (inertial same relative same position\$4)) (inertial same receiver) and accelerometer and (inertial same polygon same path)or(concentric same polygon same path)) and (base same station) (inertial same relative same position\$4)) (inertial same relative same position\$4)) (inertial same receiver) and accelerometer and (inertial same relative same position\$4)) (inertial same receiver) and accelerometer and (inertial same polygon same path)or(concentric same polygon same path)or(concentric same polygon same path)) and (base same station)) (inertial same position\$4) (inertial same polygon same path)or(concentric same polygon same path)or(concentric same polygon same path)or(concentric same polygon same same station)) (inertial same position\$4) (inertial s	3	127		_	2004/02/12 13:58
((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path) and (base same receiver) and accelerometer and (inertial same polygon same path)) and (base same receiver) and accelerometer and (inertial same polygon same path)) and (base same receiver) and accelerometer and (inertial same polygon same path)) and (base same station) ((GPS same receiver) and accelerometer and (inertial same polygon same path)) and (base same station) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) ((GPS same receiver) and accelerometer and (inertial same position\$4) ((GPS same receiver) and accelerometer and (inertial same position\$4)) ((GPS same receiver) and accelerometer and (inertial same position\$4)) ((GPS same receiver) and accelerometer and (inertial same path) or (concentric same polygon same path)) and (base same station)) ((GPS same receiver) and accelerometer and (inertial same position\$4)) ((GPS same receiver) and accelerometer and (inertial same position\$4)) ((SPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4) (GPS) and receiver and accelerometer and (inertial same position\$4) (GPS) and receiver and accelerometer and (inertial same position\$4) (GPS) and receiver and accelerometer and (inertial same position\$4) (GPS) and receiver and accelerometer and (inertial same position\$4)			(inertial same relative same position\$4)	US-PGPUB;	
((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same receiver) and accelerometer and (inertial same relative same position\$4)) ((parallel same line same path)) and ((parallel same line same path)) and ((parallel same line same path)) and ((parallel same line same position\$4)) ((parallel same line same path)) and (base same relative same position\$4)) ((gPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and (inertial same relative same position\$4)) (GPS same receiver) and accelerometer and (inertial same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same same path) or (concentric same polygon same path)) and (base same same path) or (concentric same polygon same path)) and (base same same path) or (concentric same polygon same path) or (concentric same polygon) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)			-	EPO; JPO;	
1				DERWENT;	
((parallel same line same path)or(concentric same polygon same path)) and (base same station) and (position\$4 same correct\$4) and (path same offset)) and ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) 211 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station) 6 0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((inertial same path)or(concentric same polygon same path)) and (base same station)) 7 336 (GPS same receiver) and accelerometer and (inertial same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) (GPS) and receiver and accelerometer and (inertial) (GPS) and receiver and accelerometer and (inertial) (GPS) and receiver and accelerometer and (inertial) (GPS) and receiver and accelerometer and (inertial)				IBM_TDB	
same polygon same path))and (base same station) and (position\$4 same correct\$4) and (path same offset)) and ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) 211 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station) 6 0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) 7 336 (GPS same receiver) and accelerometer and (inertial same position\$4) ((parallel same line same polygon same path)) and (base same station)) 8 0 ((vehicle or tractor or aggricultur\$4) and (inertial same position\$4) ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) 9 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) 18 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or (concentric same polygon same path)) and (base same station)) 19 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or (concentric same polygon same path)) and (base same station)) 19 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or (concentric us-pGPUB; EPO; JPO; DERWENT; IBM_TDB) 2004/02/12 13:	4	0	((vehicle or tractor or aggricultur\$4)and	USPAT;	2004/02/12 13:57
station) and (position§4 same correct§4) and (path same offset)) and ((GPS same receiver) and accelerometer and (inertial same relative same position§4)) 211 (vehicle or tractor or aggricultur§4) and (parallel same line same path) or (concentric same polygon same path)) and (base same station) 6					
(path same offset)) and ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) 211 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) 6	ŀ				
receiver) and accelerometer and (inertial same relative same position\$4)) 211 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) 6 0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) us-PGPUB; EPO; JPO; DERWENT; IBM_TDB (vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) 7 336 (GPS same receiver) and accelerometer and (inertial same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (dease same station)) 8 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (vehicle or tractor or aggricultur\$4) and (vehicle or tractor or aggricultur\$4] and (vehicle or tr					
same relative same position\$4)) (vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same same path) and (inertial same relative same position\$4)) (GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and (vehicle or tractor or aggricultur\$4) and (parallel same line same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) (GPS same receiver) and accelerometer and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) and (base same station)) and ((GPS same receiver) and accelerometer and accelerometer and (inertial same position\$4) ((parallel same line same path) or(concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial same position\$4))			1 <u>*</u>	TRW_IDB	
211 (vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station) 0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and (vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) 7 336 (GPS same receiver) and accelerometer and (inertial same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same station)) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial same position\$4) (inertial) 9 455 (GPS) and receiver and accelerometer and (inertial same position\$4) (inertial)			,		
((parallel same line same path)or(concentric same polygon same path)) and (base same station) ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) ((operallel same position\$4) ((operallel same position\$4) ((operallel same position\$4) ((operallel same line same path) or (concentric same polygon same path)) and ((parallel same line same path)) and ((parallel same line same path)) and ((parallel same path)) and (base same station)) and ((operallel same path)) and (base same path)) and (base same polygon same path)) and (base same path) and (base same polygon same path)) and (base same polygon same path)) and (base same polygon same path)) and (base same polygon same path) and (base same polygon same path) and (base same polygon same path)) and (base same polygon same path) and (base same polygon same path)) and (base same polygon same path) and (base same polygon same path) and (base same polygon same polygon same path) and (base same polygon same path) and (base same polygon same polygon same path) and (base same polygon same polygon same path) and (base same polygon same path) and (base same polygon same polygon same path) and (base same polygon polygon same polygon same polygon polygon same polygon polygon polygon polygon same polygon pol	5	211		IISDAT:	2004/02/12 13.50
same polygon same path)) and (base same station) 0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) uspAT; uspeque, and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) 17 336 (GPS same receiver) and accelerometer and (inertial same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and ((parallel same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (same path)) and (same path)) and (same path) and (same path)) and (-			•	2001/02/12 13.39
station) O ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) O ((vehicle or tractor or aggricultur\$4) and (inertial same position\$4) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path) or (concentric same polygon same path) or (concentric same position\$4) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station)) and (inertial same position\$4) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station)) and (inertial same position\$4)) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station)) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path)) and (base same station) O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path) or (concentric us-popub); O ((vehicle or tractor or aggricultur\$4) and (inertial same polygon same path) and (inertial same polygon same path) and (inertial same inertial same inerti					
0 ((GPS same receiver) and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)) and (base same station)) 7 336 (GPS same receiver) and accelerometer and (inertial same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same polygon same path)) and (base same path) or (concentric same polygon same path) or (concentric same polygon same path)) and (base same polygon same path) and (base same position\$4) 9 455 (GPS) and receiver and accelerometer and (inertial)					
(inertial same relative same position\$4)) and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path)or(concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial) 455 (GPS) and receiver and accelerometer and (inertial) (inertial)				IBM_TDB	
and ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial) 455 (GPS) and receiver and accelerometer and (inertial) 456 (GPS) and receiver and accelerometer and (inertial) 457 (GPS) and receiver and accelerometer and (inertial) 458 (GPS) and receiver and accelerometer and (inertial)	6	0	((GPS same receiver) and accelerometer and	USPAT;	2004/02/12 13:58
aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same same polygon same path)) and (base same polygon same path)) and (base same path) and (base same path) and (base same path)) ((parallel same line same path) or (concentric same polygon same path)) and (base same path) ((parallel same line same path) or (concentric same polygon same path)) and (base same path) ((parallel same line same path) or (concentric same polygon same path)) ((parallel same line same path) or (concentric same path) or (concentric same polygon) ((parallel same line same path) or (concentric same same path)) ((parallel same line same path) or (concentric same same path) ((parallel same line same path) or (concentric same same path) ((parallel same line same path) or (concentric same same same path) ((parallel same line same path) or (concentric same same same same same same same same					
path)or(concentric same polygon same path))and (base same station)) 336 (GPS same receiver)and accelerometer and (inertial same position\$4) 8 0 ((vehicle or tractor or aggricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same polygon same path)) and (base same station)) and ((GPS same receiver)and accelerometer and (inertial same position\$4)) 9 455 (GPS)and receiver and accelerometer and (inertial) 456 (IBM_TDB (USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB (USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB (Inertial)					
path)) and (base same station)) (GPS same receiver) and accelerometer and (inertial same position\$4) (vehicle or tractor or aggricultur\$4) and (parallel same line same path) or (concentric same polygon same path)) and (base same position\$4)) (GPS same receiver) and accelerometer and (inertial same position\$4)) (GPS) and receiver and accelerometer and (inertial)				· ·	
(GPS same receiver) and accelerometer and (inertial same position\$4) (inertial same line same path) or (concentric same polygon same path)) and (base same station)) and (inertial same position\$4) (inertial) (ine				IBW_LDB	
(inertial same position\$4) (inertial same path) or (concentric same polygon same path) and (base same station) and (inertial same position\$4)) (inertial same position\$4)) (inertial same position\$4) (inertial same path) or (concentric us-pequal) (ine	7	226		HICDAT.	2004/02/12 13:58
8 0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) 456 (GPS) and receiver and accelerometer and (inertial) 457 (GPS) and receiver and accelerometer and (inertial) 458 (GPS) and receiver and accelerometer and (inertial)	'	336		1	2004/02/12 13.38
0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) 456 (Inertial) DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB			(Incicial same position(4)		
0 ((vehicle or tractor or aggricultur\$4) and ((parallel same line same path) or (concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) 456 (Inertial) 1BM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB					
((parallel same line same path)or(concentric same polygon same path)) and (base same station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB					
same polygon same path))and (base same station)) and ((GPS same receiver)and accelerometer and (inertial same position\$4)) 9 455 (GPS)and receiver and accelerometer and (inertial) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	8	0	((vehicle or tractor or aggricultur\$4)and	USPAT;	2004/02/12 13:58
station)) and ((GPS same receiver) and accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB					
accelerometer and (inertial same position\$4)) 9 455 (GPS) and receiver and accelerometer and (inertial) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB					·
position\$4)) (GPS) and receiver and accelerometer and (inertial) USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB			, , , , , , , , , , , , , , , , , , , ,		
9 455 (GPS) and receiver and accelerometer and USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	f			1811_108	
(inertial) US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	9	455		IISPAT.	2004/02/12 14:00
EPO; JPO; DERWENT; IBM_TDB		133			2001, 02, 12 14.00
DERWENT; IBM_TDB	1		· · · · · · · · ·	•	
10 336 ((GPS same receiver) and accelerometer and USPAT; 2004/02/12 13:				_	.
	10	336			2004/02/12 13:59
(inertial same position\$4)) and ((GPS) and US-PGPUB;					
receiver and accelerometer and (inertial)) EPO; JPO;			receiver and accelerometer and (inertial))		
DERWENT; IBM TDB				1	
	111	ი	((vehicle or tractor or aggricultur\$4) and		2004/02/12 13:59
((parallel same line same path)or(concentric US-PGPUB;					
same polygon same path))and (base same EPO; JPO;					
station)) and ((GPS)and receiver and DERWENT;			station)) and ((GPS)and receiver and		
accelerometer and (inertial)) IBM_TDB				_	
	12	367		1	2004/02/12 14:05
((parallel same line same path)or(concentric US-PGPUB;				•	
same polygon same path))and (path same EPO; JPO;					
offset) DERWENT;			OIISEL)	1	
IBM_TDB USPAT; 2004/02/12 13:	13	n .	((GPS)and receiver and accelerometer and	-	2004/02/12 13:59
(inertial)) and ((vehicle or tractor or US-PGPUB;					
aggricultur\$4) and ((parallel same line same EPO; JPO;					
path)or(concentric same polygon same DERWENT;					
path))and (path same offset)) IBM_TDB				IBM_TDB	<u></u>

14	1328	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:24
		((parallel same path))or(concentric same	US-PGPUB;	
		polygon same path))and (path same offset)	EPO; JPO; DERWENT;	İ
			IBM TDB	
15	595	(GPS) and accelerometer and (inertial)	USPAT;	2004/02/12 14:00
1 -3	3,3	(015) and 200010101101011 and (111010141)	US-PGPUB;	=====================================
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
16	20	((vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:00
		((parallel same path)or(concentric same	US-PGPUB;	
		polygon same path))and (path same offset))	EPO; JPO;	
		and ((GPS) and accelerometer and (inertial	DERWENT;	
))	IBM_TDB	0004/00/10 14 05
17	31	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:05
1		((parallel same path)or(concentric same polygon same path))and (path same offset)and	US-PGPUB; EPO; JPO;	
		accelerometer	DERWENT;	
		decelerometer	IBM TDB	
18	21	(vehicle or tractor or aggricultur\$4) and	USPĀT;	2004/02/12 14:07
		((parallel same path)or(concentric same	US-PGPUB;	
		polygon same path))and (path same offset)and	EPO; JPO;	
1		accelerometer and speed and inertial	DERWENT;	
			IBM_TDB	
19	24	, ,	USPAT;	2004/02/12 14:08
		((parallel same path)or(concentric same	US-PGPUB;	
		polygon same path))and (path same offset)and	EPO; JPO;	
		accelerometer and (relative near4 position)	DERWENT;	
27	1220	(vohigle or tractor or aggrigultures) and	IBM_TDB	2004/02/12 14:24
21	1328	<pre>(vehicle or tractor or aggricultur\$4)and (parallel same path)and (path same offset)</pre>	USPAT; US-PGPUB;	2004/02/12 14:24
1		(pararrer same path) and (path same offset)	EPO; JPO;	
			DERWENT;	
			IBM TDB	
28	25	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:38
		(parallel same path) and (path same	US-PGPUB;	' '
		offset) and receiver and accelerometer	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
29	28	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:26
		(parallel same path) and (path same	US-PGPUB;	
		offset)and (relative same position) and accelerometer	EPO; JPO;	
		accelerometer	DERWENT; IBM TDB	
30	24	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:27
		(parallel same path) and (path same	US-PGPUB;	
		offset) and (relative near4 position) and	EPO; JPO;	
1		accelerometer	DERWENT;	
			IBM_TDB	
31	91	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:27
1		(parallel near4 path) and (path near4	US-PGPUB;	
1		offset)and (relative near4 position)	EPO; JPO;	
1			DERWENT;	
22	35	(vobiale or tractor or agarigultures)	IBM_TDB	2004/02/12 14:20
32	25	(vehicle or tractor or aggricultur\$4)and (parallel near4 path)and (path same	USPAT; US-PGPUB;	2004/02/12 14:38
1		offset) and receiver and accelerometer	EPO; JPO;	
1		deliber, and receiver and accelerometer	DERWENT;	
1			IBM TDB	
33	19	(vehicle or tractor or aggricultur\$4) and	USPAT;	2004/02/12 14:41
		(parallel near4 path) and (path near4	US-PGPUB;	
		offset) and receiver and accelerometer and	EPO; JPO;	
		speed and inertial	DERWENT;	
. .			IBM_TDB	
34	70839	(parallel near4 path)	USPAT;	2004/02/12 14:41
	1		US-PGPUB;	
			EPO; JPO;	
			DERWENT; IBM TDB	
35	1	5956250.pn.	USPAT	2004/02/12 14:41
36	1	((parallel near4 path)) and 5956250.pn.	USPAT	2004/02/12 14:41
·	J	,	<u> </u>	